

ENBIS-16

The Algebraic method in experimental design

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Polynomial regression

We are familiar with the use of polynomials throughout statistics.

$$x_1, x_2^2, x_1x_2, \dots$$

EG a second order polynomial response surface in two factors is

$$f(x_1, x_2) = \theta_{00} + \theta_{10}x_1 + \theta_{01}x_2 + \theta_{20}x_1^2 + \theta_{11}x_1x_2 + \theta_{02}x_2^2$$

Polynomials are made up of monomials. Consider a set of k factors:

$$x = (x_1, \dots, x_k)$$

and non-negative integers $\alpha = (\alpha_1, \dots, \alpha_k)$ a monomial is

$$x^\alpha = x_1^{\alpha_1} x_2^{\alpha_2} \dots x_k^{\alpha_k}.$$

A monomial x^α can be represented by its exponent vector α and we can list the monomials in a model either directly or by listing a set of exponents. We shall often use the notation

$$\{x^\alpha, x \in M\}.$$

Definition

A *monomial ideal* I is an ideal for which a collection of monomials f_1, \dots, f_m such that any $g \in I$ can be expressed as a sum

$$g = \sum_{i=1}^m g_i(x) f_i(x).$$

The idea is that given a monomial ordering and an ideal expressed in terms of the G-basis, $I = \langle g_1, \dots, g_m \rangle$, any polynomial f has a unique remainder with respect to the quotient operation $K[x_1, \dots, x_k]/I$. That is

$$f = \sum_{i=1}^m s_i(x) g_i(x) + r(x)$$

We call the remainder $r(x)$ the *normal form* of f with respect to I and write $NF(f)$. Or, to stress the fact that it may depend on \prec , we write $NF(f, \prec)$.

The algebraic method in design

We should think of design as lists of points,

$$D = \{x^{(1)}, \dots, x^{(n)}\},$$

in R^k . As algebraic varieties they have associated ideal

$$I(D) = \{f : f(x) = 0, x \in D\}$$

The use of polynomials to define design is clearly not new. For example a 2^k full factorial designs give by $\{\pm 1, \dots, \pm 1\}$ is expressed the by the solution of the simultaneous equations:

$$\{x_i^2 - 1 = 0, i = 1, \dots, k\}.$$

To obtain fractions we impose additional equations: e.g. $x_1 \dots x_k = 1$.

Step by step approach

- Choose a design D
- Select a monomial term ordering, \prec
- Compute Gröbner basis for $I(D)$ for given monomial ordering, \prec .
- The quotient ring

$$K[x_1, \dots, x_k]/I(D)$$

of the ring of polynomials $K[x_1, \dots, x_k]$ in x_1, \dots, x_k forms a vector space spanned by a special set of monomials: $x^\alpha, \alpha \in L$. These are all the monomials not divisible by the leading terms of the G-basis and $|L| = |D|$.

- The set of multi-indices L has the “order ideal” property: $\alpha \in L$ implies $\beta \in L$ for any $0 \leq \beta \leq \alpha$. For example, if $x_1^2 x_2$ in the model so is $1, x_1, x_2, x_1 x_2$. (Hierarchical model).

- Any function $y(x)$ on D has a unique polynomial interpolator given by

$$f(x) = \sum_{\alpha \in L} \theta_{\alpha} x^{\alpha}$$

such that $y(x) = f(x)$, $x \in D$.

- The cardinality of the design and the quotient basis (model) is the same: $|L| = |D|$.
- The X -matrix is $n \times n$, has full rank n and has rows indexed by the design points and columns indexed by the basis:

$$X = \{x^{\alpha}\}_{x \in D, \alpha \in L}$$

Response surface design

Response surface design, non-standard: a 16-point design which is a 5^2 factorial with all internal points (a 3^2 design) removed:

$$\begin{array}{cccc} (2, 0) & (2, 1) & (2, 2) & (1, 2) \\ (0, 2) & (-1, 2) & (-2, 2) & (-2, 1) \\ (-2, 0) & (-2, -1) & (-2, -2) & (-1, -2) \\ (0, -2) & (1, -2) & (2, -2) & (2, -1) \end{array}$$

The design ideal is generated by the following polynomials $x_2^5 - 5x_2^3 + 4x_2$, $x_1^5 - 5x_1^3 + 4x_1$, $x_1^2x_2^2 - 4x_1^2 - 4x_2^2 + 16$. It can be shown that for any term ordering, the above polynomials form a so-called reduced Gröbner basis and thus the design identifies a single model with terms $1, x_2, x_2^2, x_2^3, x_2^4, x_1, x_1x_2, x_1x_2^2, x_1x_2^3, x_1x_2^4, x_1^2, x_1^2x_2, x_1^3, x_1^3x_2, x_1^4, x_1^4x_2$.

Graeco Latin square

$A\alpha$	$B\beta$	$C\gamma$	$D\delta$
$B\gamma$	$A\delta$	$D\alpha$	$C\beta$
$C\delta$	$D\gamma$	$A\beta$	$B\alpha$
$D\beta$	$C\alpha$	$B\delta$	$A\gamma$

Code up the design point using indicator functions.

Estimable terms

1, $u[4]$, $u[3]$, $u[2]$, $t[4]$, $t[3]$, $t[2]$, $c[4]$, $c[3]$, $c[2]$, $r[4]$, $r[3]$, $r[2]$,
 $t[4]u[4]$, $t[4]u[3]$, $t[4]u[2]$

Checkdegreesoffreedom :

$16 - (1+4 \times 3) = 3$ df for interactions

Fans: a Latin Hypercube example

Design $d = 3, n = 6$

$$(0, 0, 0), (1/5, 1, 4/5), (2/5, 3/5, 2/5),$$

$$(3/5, 4/5, 1/5), (4/5, 1/5, 1), (1, 2/5, 3/5)$$

The collection of all models identifiable is called the *algebraic fan*. This design identifies 27 different models which can be classified in only six types of models, up to permutations of variables:

$1, x_1, x_1^2, x_1^3, x_1^4, x_1^5$ (3 models); $1, x_1, x_1^2, x_1^3, x_1^4, x_2$ (6 models);
 $1, x_1, x_1^2, x_1^3, x_2, x_1 x_2$ (6 models); $1, x_1, x_2, x_1^2, x_1 x_2, x_2^2$ (3 models);
 $1, x_1, x_2, x_3, x_1^2, x_1^3$ (3 models) and $1, x_1, x_2, x_3, x_1^2, x_1 x_2$ (6 models).

The fan of fractions of 2^d

- Very rich families of models, designs with enormous fans

Name	d	n	Fan size
2_{III}^{4-1}	4	8	4
2_{IV}^{4-1}	4	8	12
PB8	7	8	218
2_{IV}^{7-2}	7	32	132
2_{IV}^{7-2} (mga)	7	32	1708
2_{IV}^{7-2} (rnd)	7	32	$\sim 270,000$
PB12	11	12	$\sim 300,000$

- Exact computations only feasible for small cases.
- Aliasing structure for PB designs very complicated

Aliasing

Let $I(D)$ be the design ideal and for two polynomials f, g define

$$f(x) \sim_D g(x)$$

to mean $f(x) = g(x)$, $x \in D$. This is equivalent to

$$f(x) - g(x) \in I(D).$$

Again equivalently we have, with respect to a particular monomial ordering

$$NF(f) = NF(g)$$

The G-basis for the design ideal gives the aliasing structure:

$$LT(g) = \sum_{\alpha \in L} c_{\alpha} x^{\alpha}, \quad g \in G$$

. We can think of any large term as mapped first to a $LT(g)$.

A duality result

Given a design D embedded in a full factorial F , that is to say a fraction of a full factorial, we can consider the complementary design (fraction) $\bar{D} := F \setminus D$. Our main result says that the basis of the complementary design is the Alexander dual (relative to F) of the basis of the original design. Put as succinctly as possible:

$$L^*(D) = L(\bar{D}) \quad (1)$$

Let \prec be a fixed monomial ordering; let F be a full factorial design F with a fraction $D \subset F$. Then the bases of the quotient rings of D and the complementary design $\bar{D} = F \setminus D$ are Alexander dual, relative to F .

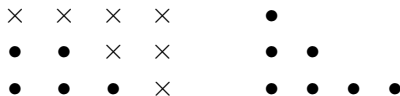
An example

A subset of a 4×3 design.

The crosses represent term exponents in $L(F) \setminus L(D)$. The Alexander dual $L^*(D)$ is obtained by flipping the crosses to give the right panel in the same figure. In this example, the Alexander dual of

$L(D) = \{1, x_1, x_2, x_1^2, x_1x_2, x_1^2\}$ relative to the 4×3 full factorial is

$L^*(D) = \{1, x_1, x_2, x_1^2, x_1x_2, x_2^2, x_1^3\}$.



Transects 1. Interpolation on transects

Consider the equation $x_1x_2 = 0$. The G-basis of $\langle x_1, x_2 \rangle$ is itself. This says that we take all terms

$$1, x_1, x_1^2, \dots, x_2, x_2^2, \dots$$

which means all polynomial additive models

$$\theta_{00} + \theta_{10}x_1^2 + \theta_{20}x_1^2 + \dots + \theta_{01}x_2^2 + \theta_{01}x_2^2 + \dots$$

Now combine it with a design $\langle x_1^2 - 1, x_2^2 - 1 \rangle$. We want to interpolate on the lines $x_1x_2 = 0$ AND the points $(\pm 1, \pm 1)$. We need to represent OR that is union of varieties:

$$\langle x_1x_2(x^2 - 1), x_1x_2(x_2^2 - 1) \rangle$$

The leading terms are

$$x_1^3x_2, x_1x_2^3$$

↑

o	x	x	x	x	x
o	X	x	x	x	x
o	o	o	x	x	x
o	o	o	X	x	x
o	o	o	o	o	o

→

Using the Normal Form

Truncate the Taylor expansion of some function. Eg

$$(1 + \exp(x_1))(1 + \exp(x_2))$$

Truncated form up to degree 3.

$$\begin{aligned} & 1 + x_1 + \frac{x_1^2}{2} + \frac{x_1^3}{6} + \dots + \frac{x_2^2}{2} + \frac{x_2^3}{6} + \dots \\ & \quad x_1 x_2 + \frac{x_1^2 x_2}{2} + \frac{x_1 x_2^2}{2} + \frac{x_1^2 x_2^2}{4} + \dots \\ & \quad \frac{x_1^3 x_2}{6} + \frac{x_1 x_2^3}{6} + \frac{x_1^3 x_2}{6} + \frac{x_1 x_2^3}{6} + \frac{x_1^3 x_2}{12} + \frac{x_1^2 x_2^3}{12} + \frac{x_1^3 x_3}{36} \end{aligned}$$

Normal forms wrt $\langle x_1 x_2 (x_1^2 - 1), x_1 x_2 (x_2^2 - 1) \rangle$

$$\begin{aligned} & 1 + x_1 + \frac{x_1^2}{2} + \frac{x_1^3}{6} + \dots + x_1 + \frac{x_2^2}{2} + \frac{x_2^3}{6} + \dots \\ & \quad \frac{49}{12} x_1 x_2 + \frac{7}{12} x_1^2 x_2 + \frac{7}{12} x_1 x_2^2 + \frac{1}{4} x_1^2 x_2^2 \end{aligned}$$

A general class of designs

Observe on hyperplanes, lines, points. We wish to develop an aliasing theory for such *hyperplane arrangements*.

Simple example: 3 line in R^2 .

$$(x_1 + x_2 - 1)(x_1 - x_2 - 1)(2x_1 + x_2 - 1)$$

Multiply out: $2x_1^3 + \dots$. Clear that with the right \prec we have $LT = x_1^3$

\uparrow	\uparrow	\uparrow			o
o	o	x	x	x	
o	o	o	x	x	x
o	o	o	x	x	x
o	o	o	X	x	x

A differencing trick

Take the quotient ring defined by

$$\langle x_1x_2(x^2 - 1), x_1x_2(x_2^2 - 1) \rangle$$

and remove the terms defined by $\langle x_1x_2 \rangle$. Solution:

$$\{x_1x_2, x_1^2x_2, x_1x_2^2, x_1^2x_2^2\}$$

↑

x	x	x	x	x	x
x	X	x	x	x	x
x	o	o	x	x	x
x	o	o	X	x	x
x	x	x	x	x	x

→

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